



v0gw1 K MwZ

fvqKv

cfeRvi BD1b1U Avgiv MwZ mspvš-ivikgvjv, h_v- miY, telM, ZjY Ges Ae`vb tf±i vbtq AvtjvPbv Kti1Q| GQvov AvtjvPbv Kti1Q cñ½ ve`yl cñ½ KvVtgv m±útkK⁹ Gici GKgw1K Z_v mij `i1LK MwZ eY0vq Avgiv Zv e`envi Kti1Q| GKgw1K MwZ1elqK tj L1P1, ci šye`ž mgxKiY Ges Avtci1K te1Mi aviYv mýúó Kiv ntqtQ| Avgiv BwZgta` AvtjvPbv Kti1Q GKgw1K cñ½ KvVtgv1 gtZv v0gw1K Ges v1gw1K cñ½ KvVtgv1Z e`K1Yvi miY m±útkK⁹

G Aa`vtq Avgiv v0gw1K cñ½ KvVtgv1Z Z_v mgZtj MwZkxj e`ž t111 H mKj ivikgvjvi AeZviYv Kie| v0gw1K MwZ1Z telM Ges Zj1Yi tf±i ifc fvj f1te Dcjwä Kiv hvq| GB MwZ1Z e`KYv GKB tiLv ev A1 eivei MwZkxj nte Ggb tKvb K_v bvB| eis `v A11i m1c11 ev mgZtj i Dci e`K1Yvi MwZkxj Zv1KB GLv1b AvtjvPbv Kiv nte| GKgw1K MwZi t111 j x ivikgvjv mn1RB v1gw1K MwZi t111 m±útmw1 Z Kiv hvte| G BD1b1U Avgiv mgZj xq v0gw1K MwZ AvtjvPbvq mxgve x_vKe| D`vniY v1tmte c111 e`ž MwZ Ges e1xq MwZi AvjvPbv AšF1 nte|

cW - 1

Muz velqK iukgvj vi Ges Muzi mgxKiY mgfni wogwilk tf±i ifc

Dfik

G crtVi tktl Avicub-

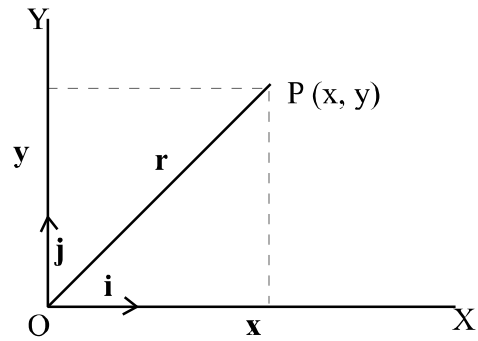
- 1 wogwilk ch½ KivrtgvZ tkvb we`y Ae`vb tf±i wbyq KitZ cvi`eb,
- 1 Muzmspviš-wefbci vktK cõqRb Abgvrti wogwilk KivrtgvZ tf±i ifc cõk KitZ cvi`eb,
- 1 wogwilk Muzi tñtñ Muzi mgxKiY mgfni tf±i ifc cõZc`b KitZ cvi`eb|

3.1.1 Muz velqK iukgvj vi tf±i cõk

Avgiv ceZrBDibtu Avtj vPbv KtiwQ th, ch½ Kivrtgvi gj- we`y mvtctñ tkvb we`y Ae`vbtk th tf±i w`tq eSv`bv nq ZvtK Ae`vb tf±i etj [AbtQ` 1.1] Ae`vb tf±i tk r ðviv cõk Kiv nq| wogwilk tñtñ x Añ l y Atñi mvtctñ GKw we`y `vbr¼ wpyZ nq `w iuk w`tq| GKw x Añ t`tk we`y `iZ; Ab`w y-Añ t`tk we`y `iZ| Avgiv wj wL P we`y `vbr¼ (x, y) ev mstñtc p(x,y) | x, l y Atñi tQ` we`y jK gj- we`y (0, 0) aiv nq| gj- we`y mvtctñ P we`y Ae`vb tf±i $r = xi + yj \dots \dots \dots (3.1)$

GLv`b i, j h`vµtg x l y Añ AwfgjL GKK tf±i |

wZxq BDibtu Avgiv t eavg x tj L wPñ Avtj vPbv KtiwQ| tmLvtb Muzkxj e`zngtqi mvtctñ GKB tiLv eivei Muzkxj t`tkQ| G BDibtu NUbv wKQy Avj v`vrt`e Dc`vcb Kiv nte| Gtñtñ tiLvi cwi etZ`e`Kvi `vbrš` nte xy mgZtj | e`z Muzc_ t`Lvb nte wogwilk KivrtgvZ| tkvb e`z Muzc_ tk AtbK mgq Avgiv c`tiLv (Trajectory) etj AwfwnZ Kie|



wPñ 3.1

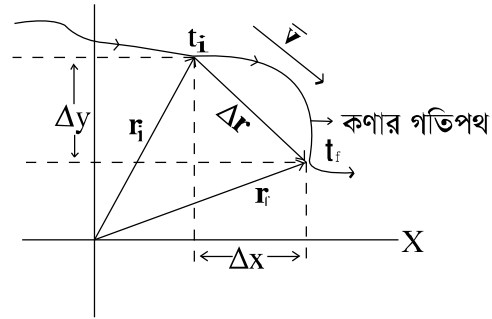
3.2 bs wPñ GKw e`z cõg Ae`vb r_i tk l Ae`vb r_f Ges e`z miY Δr t`Lvtbv nj | mi`yi w`K Aw` Ae`vb t`tk tk l Ae`v`bi w`tk | cõg Ae`v`b e`z Ae`vb tf±i r_i Ges tk l Ae`v`b e`z Ae`vb tf±i r_f |

GL1tb $\Delta \mathbf{r} = \mathbf{r}_f - \mathbf{r}_i$
 $= (x_f \mathbf{i} + y_f \mathbf{j}) - (x_i \mathbf{i} + y_i \mathbf{j})$
 $= (x_f - x_i) \mathbf{i} + (y_f - y_i) \mathbf{j}$

ev, $\Delta \mathbf{r} = \Delta x \mathbf{i} + \Delta y \mathbf{j} \dots \dots \dots (3.2)$

GL1tb $\Delta x = x_f - x_i$ Ges $\Delta y = y_f - y_i$

h_vμtg x Ges y A¶i eivei e`z mi tYi Dcisk/



¶PÎÑ 3.2

teM

th tKvb mg tqi e`ear tb tKvb e`z Mto GKK mg tq th mi Y nq ZtK e`z Mo teM etj | Δt mg tqi e`ear tb tKvb e`z mi Y Δr ntj Mo teM

$\bar{\mathbf{v}} = \frac{\Delta \mathbf{r}}{\Delta t}$ (Mo eSv bvi Rb` tKvb cZxKi Dci 0—0 evi ¶Py e`eüZ nq)

ev, $\bar{\mathbf{v}} = \frac{\Delta (x\mathbf{i} + y\mathbf{j})}{\Delta t}$

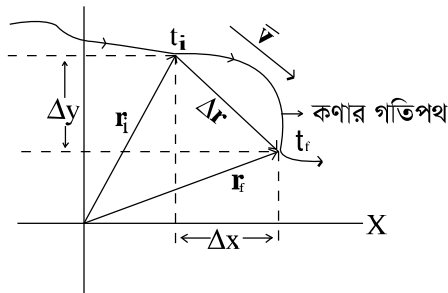
ev, $\bar{\mathbf{v}} = \frac{\Delta x \mathbf{i} + \Delta y \mathbf{j}}{\Delta t}$

ev, $\bar{\mathbf{v}} = \frac{\Delta x}{\Delta t} \mathbf{i} + \frac{\Delta y}{\Delta t} \mathbf{j} = \bar{v}_x \mathbf{i} + \bar{v}_y \mathbf{j}$

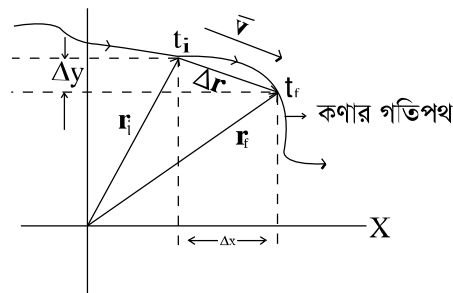
GB Mo teMi w`K Δr Gi w`K | ¶PÎ (3.2)

mg tqi e`ear b k`b`i mgiceZPntj Mo teMi mwgwŠK Ae`vi (in the limit) gvb tK Zvr¶wYK teM ev teM etj,

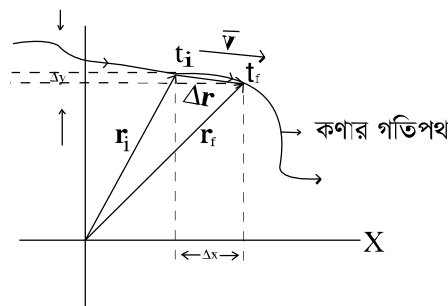
$\mathbf{v} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \mathbf{r}}{\Delta t} = \frac{d\mathbf{r}}{dt} \dots \dots \dots (3.3)$



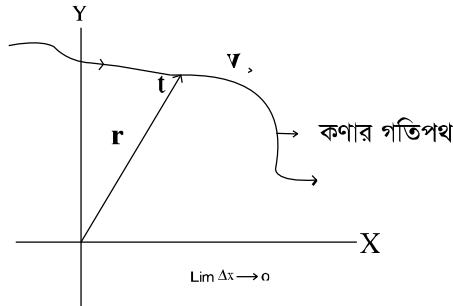
¶PÎÑ 3.3 (K)



¶PÎÑ 3.3 (L)



¶PÎÑ 3.3 (M)



¶PÎÑ 3.3 (N)

WPT 3.3 Gi K, L I M-G t`Lv nqtQ tKvb e`z Mvzi tqt mgqi e`eavb Δt μgk Ktg hv`Q | GLv`b e`z Mvzct`i tjL WPTi Dci GKwJ mrgmSK c`uqv eSv`bvi tPov Kiv nqtQ | K t`K M WPTi q`z`t`K q`z`zi mgq e`eavb t`Lv nqtQ | mgqi e`eavb wmvte`i mve`avi Rb` t`K w`i ti`L t`K t`K Gi mgx`ceZP Kiv nqtQ | mrgmSK gv`bi tqt Δr Mvzct`i `uk`Ki mgv`stv`j nq | Gi Awfgly nq Mvzi w`K | wK`zhLb t`K Ges t`K Gi cv`R` Ly Kg nq | A`P $\Delta t \rightarrow 0$ nq, ZLb Mvz ct`i tKvb w`z` teM v Gi w`K nq H w`z` AswKZ `uk`R eivei (WPT 3.3 N) |

mgv`Ki Y 3.3 t`K t`Lv hv`Q teM v nqt mgqi mvtct`q Ae`vb t`f`ti i cwieZ`bi nvi | th`nZz

$$\mathbf{r} = x\mathbf{i} + y\mathbf{j}$$

$$\mathbf{v} = \frac{d}{dt}(x\mathbf{i} + y\mathbf{j})$$

$$= \frac{dx}{dt}\mathbf{i} + \frac{dy}{dt}\mathbf{j}$$

wK`z` $\frac{dx}{dt}$ nqt mgqi mvtct`q x `vbst`Ki cwieZ`bi nvi hv` x- A`q eivei e`z tetMi Dcisk v_x |

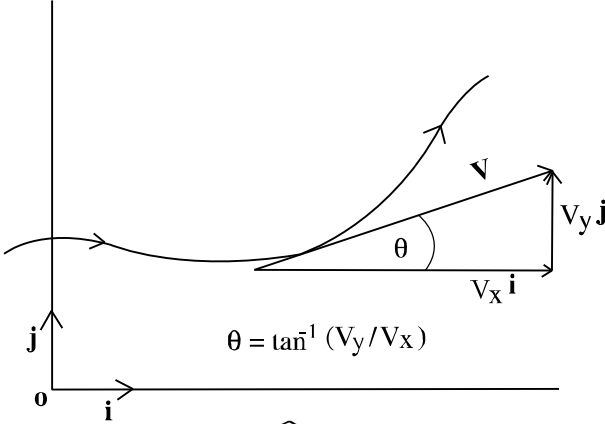
Abj`c fiv`e $\frac{dy}{dt}$ nte y A`q eivei e`z tetMi Dcisk v_y |

$$\therefore \mathbf{v} = v_x\mathbf{i} + v_y\mathbf{j} \dots \dots \dots (3.4)$$

tetMi gv`b A`P `wZ v nqt

$$v = \sqrt{v_x^2 + v_y^2} \dots \dots \dots (3.5)$$

Mvz`k`j e`z`i th tKvb gv`z`P tetMi w`K teM t`f`ti v l x- A`q`i A`sf`y tKvY θ θ viv eY`v Kiv hvq |



WPT 3.4

WPT 3.4 t`K t`Lv hvq, $\tan\theta = \frac{v_y}{v_x}$

ev $\theta = \tan^{-1}\left(\frac{v_y}{v_x}\right) \dots \dots \dots (3.6)$

ZjY

th tKvb mgq e`earfb tKvb e`z Mto cZ GKK mgq tetMi th cwieZB nq ZvB Mo ZjY | Δt mgqti e`earfb tKvb MvZkxj e`z tetMi cwieZB Δv ntj Mo ZjY

$$\bar{a} = \frac{\Delta v}{\Delta t} \text{ GLvfb Mo eSvZ a-Gi Dci eri } \hat{0}-\hat{0} \text{ Pý e`eüZ ntqtQ}$$

$$\text{er } \bar{a} = \frac{\Delta v_x}{\Delta t} \mathbf{i} + \frac{\Delta v_y}{\Delta t} \mathbf{j}$$

$$= \bar{a}_x \mathbf{i} + \bar{a}_y \mathbf{j} \dots \dots \dots (3.7)$$

GB Mo ZjYi w`K Δv Gi w`K | mgq e`earb k#`i mgxvZP ntj Mo ZjYi mvgwšK gubtK ZvrwYK ZjY ej v nq | A_#

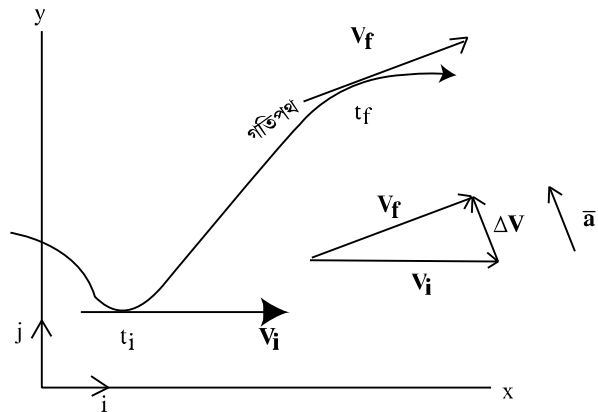
ZvrwYK ZjY,

$$\mathbf{a} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \mathbf{v}}{\Delta t} = \frac{d\mathbf{v}}{dt} \dots \dots \dots (3.8)$$

mgxKi Y (3.8) t`K t`Lv hv`Q ZjY \mathbf{a} nt`Q mgqti mvtct` tetMi cwieZ#bi nvi $\frac{dv}{dt}$ |

thtnZz

$$\begin{aligned} \mathbf{v} &= v_x \mathbf{i} + v_y \mathbf{j} \\ \therefore \mathbf{a} &= \frac{d}{dt} (v_x \mathbf{i} + v_y \mathbf{j}) \\ &= \frac{dv_x}{dt} \mathbf{i} + \frac{dv_y}{dt} \mathbf{j} \end{aligned}$$



WPIÑ 3.5

wKšZ $\frac{dv_x}{dt}$ nt`Q mgqti mvtct` e`z tetMi x Dcivtki cwieZ#bi nvi A_# x A` eivei ZjYi

$$\text{Dcivsk } a_x = \frac{dv_x}{dt} \text{ |}$$

$$\text{Abjyc fite y A` eivei ZjYi Dcivsk } \frac{dv_y}{dt} = a_y$$

$$\therefore \mathbf{a} = a_x \mathbf{i} + a_y \mathbf{j} \dots \dots \dots (3.9)$$

3.1.2 Muzi mgxKiYi tƒ±i iƒc cÛZcv`b

BDwbU -2 G Avgiv GKgwîK cñ½ KvWtçvZ Muzi mgxKiY mgr cÛZcv`b KtiwQ| GLb Avgiv mgZtj A_ƒ w-gwîK Muzi tƒt Muzi mgxKiY, t j v cÛZcv`b Kie| aiv hvK t mgtq Muzkxj tKvb e^{-z},

$$Ae^{-vb} tƒKUi, \mathbf{r} = x\mathbf{i} + y\mathbf{j} \dots \dots \dots (3.9a)$$

$$teM, \mathbf{v} = v_x \mathbf{i} + v_y \mathbf{j} \dots \dots \dots (3.9b)$$

$$ZjY, \mathbf{a} = a_x \mathbf{i} + a_y \mathbf{j} \dots \dots \dots (3.9c)$$

AvtMi gZB Avgiv mgZj tY Muzkxj e^{-z} Rb` mgxKiY, wj cÛZcv`b Kie| A_ƒ ZjY a = a`eK| aiv hvK, mgq MYbri i i`tZ A_ƒ hLb t = 0 ZLb e^{-z} i Aw` Ae^{-vb} tƒ±i r₀ Ges Aw` teM v₀ |

A_ƒ Dcvstki mrvth` wj Ltj

$$Aw` Ae^{-vb} tƒ±i, \mathbf{r}_0 = x_0\mathbf{i} + y_0\mathbf{j} \dots \dots \dots (3.10a)$$

$$Aw` teM, \mathbf{v}_0 = v_{x0} \mathbf{i} + v_{y0} \mathbf{j} \dots \dots \dots (3.10b)$$

Gevi mgZj tY Muzi tƒt mgxKiY, wj cÛZcv`b Kiv hvK|

$$(K) \mathbf{v} = \mathbf{v}_0 + \mathbf{a}t$$

GKgwîK Muzi tƒt Avgiv Rvb v = u + at

x Aƒ eivei Aw` teM v_{x0} Ges t mgtq teM v_x Ges ZjY a_x aitj GKgwîK Muzi mgxKiYw nte|

$$v_x = v_{x0} + a_x t$$

mgxKiYw tƒ±i iƒc wj Ltj nte,

$$v_x \mathbf{i} = v_{x0} \mathbf{i} + a_x t \mathbf{i} \quad [\because x \text{ Aƒ eivei GKK tƒ±i } \mathbf{i}]$$

Abjcfite y Aƒ eivei Muzi Rb` mgxKiY nte,

$$v_y \mathbf{j} = v_{y0} \mathbf{j} + a_y t \mathbf{j}$$

mgxKiY `w thvM Kitj cvl qv hvq,

$$v_x \mathbf{i} + v_y \mathbf{j} = v_{x0} \mathbf{i} + a_x t \mathbf{i} + v_{y0} \mathbf{j} + a_y t \mathbf{j}$$

$$ev, \mathbf{v} = (v_{x0} \mathbf{i} + v_{y0} \mathbf{j}) + (a_x \mathbf{i} + a_y \mathbf{j})t$$

$$ev, \mathbf{v} = \mathbf{v}_0 + \mathbf{a}t \dots \dots \dots (3.11)$$

$$[mgxKiY 3.10b t_ƒK v_{x0} \mathbf{i} + v_{y0} \mathbf{j} = \mathbf{v}_0$$

$$\text{Ges } 3.9c t_ƒK a_x \mathbf{i} + a_y \mathbf{j} = \mathbf{a} \text{ emtq }]$$

$$(L) \mathbf{r} = \mathbf{r}_0 + \frac{1}{2}(\mathbf{v}_0 + \mathbf{v}) t$$

$$GKgwîK Muzi tƒt Avgiv Rvb Motem \bar{v} = \frac{\mathbf{u} + \mathbf{v}}{2}$$

Ges $s = \left(\frac{u+v}{2}\right) t$

x A¶l eivei $s = x - x_0 = \left(\frac{v_{x0} + v_x}{2}\right) t$

ev, $x = x_0 + (v_{x0} + v_x) \frac{t}{2}$

ev, $x = x_0 + \frac{1}{2} (v_{x0} + v_x) t$

GB mgxKi YuWi tf±i ifc nte

$x_i = x_0 i + \frac{1}{2} (v_{x0} + v_x) t i$

Abifcfitē y A¶l eivei MwZi mgxKi YuWi tf±i ifc nte

$y_j = y_0 j + \frac{1}{2} (v_{y0} + v_y) t j$

mgxKi Y`thM Kfi cvB

$x_i + y_j = x_0 i + \frac{1}{2} (v_{x0} + v_x) t i + y_0 j + \frac{1}{2} (v_{y0} + v_y) t j$

ev, $r = (x_0 i + y_0 j) + \frac{1}{2} [(v_{x0} i + v_{y0} j) + (v_x i + v_y j)] t$

ev, $r = r_0 + \frac{1}{2} (v_0 + v) t \dots \dots \dots (3.12)$

(M) $r = r_0 + v_0 t + \frac{1}{2} a t^2$

GKgwî K MwZi t¶t¶ Avgiv Rmb $S = ut + \frac{1}{2} a t^2$

x A¶l eivei $S = x - x_0 = v_{x0} t + \frac{1}{2} a_x t^2$

ev, $x = x_0 + v_{x0} t + \frac{1}{2} a_x t^2$

GB mgxKi tYi tf±i ifc nj

$x_i = x_0 i + v_{x0} t i + \frac{1}{2} a_x t^2 i$

Abifcfitē y A¶l eivei MwZi mgxKi tYi tf±i ifc nj

$y_j = y_0 j + v_{y0} t j + \frac{1}{2} a_y t^2 j$

GB mgxKi Y`thM Kfi cvB,

$x_i + y_j = x_0 i + v_{x0} t i + \frac{1}{2} a_x t^2 i + y_0 j + v_{y0} t j + \frac{1}{2} a_y t^2 j$

ev, $r = (x_0 i + y_0 j) + (v_{x0} i + v_{y0} j) t + \frac{1}{2} (a_x i + a_y j) t^2$

ev, $r = r_0 + v_0 t + \frac{1}{2} a t^2 \dots \dots \dots (3.13)$

mvi ms†¶c

uögwi K Mo†em, $\bar{v} = \frac{\Delta r}{\Delta t}$

uögwi K Zvr¶¶YK teM, $v = \frac{dr}{dt}$

uögwi K MoZji Y, $\bar{a} = \frac{\Delta v}{\Delta t}$

uögwi K Zvr¶¶YK Zji Y $a = \frac{dv}{dt}$

mgZji †Y MuZi mgxKi †Yi uögwi K t†±i i/c

(i) $v = v_0 + a t$

(ii) $r = r_0 + \frac{1}{2}(v_0 + v) t$

(iii) $r = r_0 + v_0 t + \frac{1}{2} a t^2$

c†WËi gjˆvq

m¶K DË†i i c†k ¶K ¶y (√) w b

1/ tKvbu Mo Zji †Yi msÁv ?

(K) $\bar{a} = \frac{dv}{dt}$

(M) $\bar{a} = \frac{\Delta v}{\Delta t}$

(L) $a = \frac{dv}{dt}$

(N) $a = \lim_{\Delta t \rightarrow 0} \frac{\Delta v}{\Delta t}$

2/ tKvbu Zvr¶¶YK te†Mi msÁv ?

(K) $v = \frac{s}{t}$

(M) $\bar{v} = \frac{dr}{dt}$

(L) $v = v_0 + at$

(N) $v = \lim_{\Delta t \rightarrow 0} \frac{\Delta v}{\Delta t}$

3/ eˆz Aeˆtb t†±i ej †Z tKvbu eSvq ?

(K) $r = x i + y j$

(M) $S = (v_x i + v_y j) t$

(L) $\Delta r = \Delta x i + \Delta y j$

(N) $\Delta S = (a_x i + a_y j) t^2$

cW -2

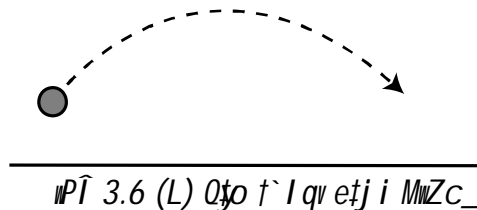
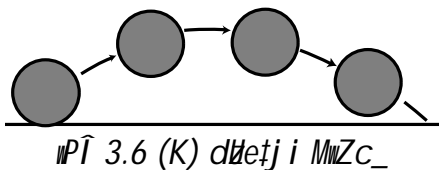
ববুণ্ণ e`zev cõmi MvZ I MvZc`i mgxKiY

G cvtVi tk`I Avcb

- | cõm vK Zv ej tZ cviteb,
- | cõmi MvZ vDgvv`K Zv e`vL`v Ki tZ cviteb,
- | cõm ev vববুণ্ণ e`z`e vDgvv`K MvZ vbañ`tYi mgxKiY cõZcv`b Ki tZ cviteb,
- | cõmi mev`vK D`PZvq IVvi mgq Kij, mev`vK D`PZv, DÇqb Kij I Avb`vugK পান্না vBYg Ki tZ cviteb|

3.2.1 vববুণ্ণ e`z`cõm

tKvb e`z`K Avb`vug`Ki mvt` vZhR fite evZv`m O`jo v`tj Zvi Dci AvfKIR ZiY KivR Kti Ges mgg``tbi c`fite e`z`e v`gk Dcti DVtZ DVtZ teM kb` nq| c`yivq e`z`e GKBfite fctõ vdti Avt`m| Avgiv d`etj j`v` gvivi `k`i m`t`½ mevB c`v`vPZ| GKvU v`Xj evZv`m O`jo t`qvi `k`I Avgiv t`tL`vQ| d`etj ev v`Xj n`tjv| cõmi D`vniY|



e`z`ZxhR fite O`jo v`tj Zv Avae`vKvi ct` Avevi fctõ vdti Avt`m| ZxhR fite vববুণ্ণ th tKvb e`z`e MvZ`K Avgiv cõm evj | evZv`m vববুণ্ণ e`z`e MvZi mgxKiY vbañ`tYi t`ñ`t` evZv`mi evav`K D`c`ñ`v Kiv nq| cõmi MvZ vDgvv`K| ZxhR fite vববুণ্ণ v`Xj, etj U, ej BZ`v`i MvZ cõm MvZi D`vniY|

cõm MvZi t`ñ`t` KivZcq ivki msAv

cõmi MvZ ms`m`v`š`Av`tj vPbvq KtqKvU ivki avi Yv , i`Zc`Y`Zv n`tj v:

- (1) vব`ñ`cb teM (Velocity of projection) t th Avv` teM cõm`K kb` ev evZv`m vব`ñ`cb Kiv nq Zv`K vব`ñ`cb teM etj |
- (2) vব`ñ`cb tKvY (Angle of projection) t vব`ñ`t`ci g`y`Z`v`v`ñ`cb teM`i Avf`g`y` Avb`vug`Ki mvt` th tKvY m`v` Kti Zv`K vব`ñ`cb tKvY etj |
- (3) vব`ñ`cb v`e``y (Point of projection) t th v`e``y` t`K cõm`v vব`ñ`ñ` nq Zv`K vব`ñ`cb v`e``y etj |
- (4) v`e`PiY c` (Trajectory) t cõmi MvZc``K ev c` ti Lv`K Gi v`e`PiY c` etj |
- (5) v`e`PiY Kij (Time of flight) t D`r`ñ`cb g`y`Z`v` t`K th mgq ci cõm mgZ`tj vdti Avt`m Zv`K v`e`PiY Kij etj |
- (6) পান্না (Range) t cõm`½ mgZ`tj i th v`e``z` cõm c`v`Z` nq Zv`K cZb v`e``y etj | vব`ñ`cb v`e``y cZb v`e``y ga`eZ`m`ij `i`v`K `i`Z`K cõmi পান্না etj |

A_{θ} , $v_x = v_0 \cos \theta_0$ Ges $v_y = v_0 \sin \theta_0 - gt \dots \dots \dots (3.15)$

AZGe t`Lv h1q th mgM0DCqbKvj e`mc tetMi x Dcisk Z_v Abf1gK Dcisk v_x Acwi ewZ`
_v`K | th tKvb gytZ`eM v ntj Gi gvb :

$|\mathbf{v}| = v = \sqrt{v_x^2 + v_y^2} \dots \dots \dots (3.16)$

Ges teM v hw` Abf1gK i mvt_ A`_ x At`i mvt_ θ tKvY DrcbaKti Zv ntj

$\tan \theta = \frac{v_y}{v_x} \dots \dots \dots (3.17)$

Ges GB tetMi w`K e`ji MvZ ct_i c0Z`K we`jz AswKZ `ukR eivei [thgb wP1 3.8 G t`Lv b v
ntqtQ] KvR Kti |

th tKvb gytZ` tZ e`ji Ae`vb tf+i r ntj Gi x l y Dcisk A`_ e`ji x l y `vbsK Avgiv
MvZi mgxKiY (3.13) t`K wby` Ki tZ cwi |

MvZ mgxKiY (3.13) nj ,

$\mathbf{r} = \mathbf{r}_0 + \mathbf{v}_0 t + \frac{1}{2} \mathbf{a} t^2$

ev, $x\mathbf{i} + y\mathbf{j} = x_0\mathbf{i} + y_0\mathbf{j} + v_{x0}t\mathbf{i} + v_{y0}t\mathbf{j} + \frac{1}{2} a_x t^2 \mathbf{i} + \frac{1}{2} a_y t^2 \mathbf{j}$
 $= 0 + 0 + (v_0 \cos \theta_0) t\mathbf{i} + (v_0 \sin \theta_0) t\mathbf{j} + 0 - \frac{1}{2} g t^2 \mathbf{j}$

ev, $x = (v_0 \cos \theta_0) t$ Ges $y = (v_0 \sin \theta_0) t - \frac{1}{2} g t^2 \dots \dots \dots (3.18)$

mZivs th tKvb gytZ` Ae`vb tf+i r Gi gvb ntj v

$|\mathbf{r}| = r = \sqrt{x^2 + y^2} \dots \dots \dots (3.19)$

Ges Ae`vb tf+i r hw` Abf1gK ev x At`i mvt_ θ' tKvY DrcbaKti Zv ntj ,

$\tan \theta' = \frac{y}{x} \dots \dots \dots (3.20)$

c0mi MvZct_i mgxKiY t tKvb e`z MvZct_i mgxKiY nt`Q th tKvb gytZ`Zvi `vbsK, tji m`uK`
wb`RK mgxKiY | aiv hvK c0mi MvZct_ GKw we`yp Gi `vbsK (x,y) mgq t Gi Atc`K |
mgxKiY (3.18) t`K t Gi Atc`K wntmte `vbsK Gi gvb x l y cvl qv hvq |
GLb GB mgxKiY, tji t`K t AcvviY Ki t j x l y Gi gta` m`uK` cvl qv hvte | (3.18) mgxKiY
`ji c0gwU t`K c0B t Gi gvb wZxqU tZ emvtj wbtPi mgxKiY wU cvl qv hvte |

$y = (v_0 \sin \theta_0) \times \frac{x}{v_0 \cos \theta_0} - \frac{1}{2} g \left(\frac{x}{v_0 \cos \theta_0} \right)^2$

ev, $y = \frac{v_0 \sin \theta_0}{v_0 \cos \theta_0} x - \frac{1}{2} \frac{g x^2}{(v_0 \cos \theta_0)^2}$

ev, $y = x \tan \theta_0 - \frac{1}{2} \left(\frac{g}{v_0^2 \cos^2 \theta_0} \right) x^2 \dots \dots \dots (3.21)$

GB mgxKiY th tKvb gytZx I y Gi m^uK^oA_{fr} AbfygK I Dj ^α^⁻vbvstKi m^uK^obt`R Kti | GB mgxKiY n^o c^otmI Pj ti Lvi mgxKiY |

GB mgxKiY

$$v_o, \theta_o \text{ Ges } g \text{ a}^eK \text{ etj } \tan\theta_o \text{ Ges } \frac{g}{2v_o^2 \cos^2\theta_o} \text{ a}^eK |$$

$$mzivs \tan\theta_o = a$$

$$\text{Ges } \frac{g}{2v_o^2 \cos^2\theta_o} = b \text{ aitj (3.21) mgxKiYiu `vovq}$$

$$y = ax - bx^2 \dots \dots \dots (3.22)$$

h_v GKiu A_ve_tEi mgxKiY | AZGe c^otmI Pj ti Lv n^o GKiu A_ve_tE |

me^oaK D^oPZv

me^oaK D^oPZvq e⁻z tetMi উল্লস Dc^osk kb^o nq, A_{fr} v_y = 0 GB ktZ^omgxKiY (3.15) t_o t Gi th gvb cvl qv hvq | aiv hvK t_m n^ote m^ote^oP D^oPZvq I Vvi mgq | A_{fr}

$$v_y = v_o \sin\theta_o - gt$$

$$0 = v_o \sin\theta_o - g t_m$$

$$\text{ev, } t_m = \frac{v_o \sin\theta_o}{g} \dots \dots \dots (3.23)$$

th tKvb ⁻v_t b g a^e i^ovk etj t_m ∝ v_o sinθ_o

mzivs t^o Lv hvq th me^oaK D^oPZvq I Vvi mgq t_m e⁻z ^obt^ocb tetMi উল্লস Dc^ost^oki mgv^og^omZK |

t = t_m mg^ot^o y Gi gvbB n^o me^oaK D^oPZv h_m |

$$(3.18) \text{ mgxKiY } y = h_m \text{ Ges } t = t_m = \frac{v_o \sin\theta_o}{g} \text{ eim^ot^o me^oaK D^oPZvi gvb cvl qv hvq,}$$

$$h_m = v_o \sin\theta_o \times \frac{v_o \sin\theta_o}{g} - \frac{1}{2g} \left(\frac{v_o \sin\theta_o}{g} \right)^2$$

$$\text{ev, } h_m = \frac{v_o^2 \sin^2\theta_o}{g} - \frac{1}{2} \frac{v_o^2 \sin^2\theta_o}{g}$$

$$\text{ev, } h_m = \frac{(v_o \sin\theta_o)^2}{2g} \dots \dots \dots (3.24)$$

th tKvb ⁻v_t b g GKiu a^ei^ovk AZGe h_m ∝ (v_osinθ_o)² A_{fr} GKiu c^om me^oaK th D^oPZvq DV^ote Zv e⁻z A_v tetMi Dj ^α^⁻Dc^ost^oki et^oM^o mgv^og^omZK | Avgiv R^ov^o θ Gi gvb 90° Gi R^o sinθ Gi gvb me^oaK nq A_{fr} sin90° = 1 (me^oaK)

AZGe h_m = $\frac{v_o^2}{2g}$ me^oaK gvb ZLbB n^ote hLb e⁻zK Lv^ov Dc^oti i ^o tK A_{fr} 90° Dr^ocb tK^oY ^obt^ocb Kiv n^ote |

DÇqb Kvj

c`mi ubt`ci ci Avevi fctô GKB Ztj wdti AvmtZ th mgq j vM ZvK DÇqb Kvj ej v nq| e`z fctô wdti Avmtj উল্লস miY kb` A_` y = 0 nq| 3.18 mgxKi tY GB kZ`emrtj c`B t Gi gvb nte DÇqb Kvj |

g`b Kwi DÇqb Kvj T

AZGe, $y = (v_o \sin \theta_o) \frac{1}{2} gt^2$ mgxKi tY Dj `mi Y, $y = 0$ Ges DÇqb Kvj =T emtq

$$0 = (v_o \sin \theta_o) T - \frac{1}{2} gT^2$$

$$\therefore T = 0 \text{ ev, } T = \frac{2v_o \sin \theta_o}{g} \dots \dots \dots (3.25)$$

th`nZz = 0 fctô t`K th gytZ`e` ubt`c Kiv n`Q tmB mgq ubt`R Kti | ZvB GuU M`b thvM` bq

m`zivs $T = \frac{2v_o \sin \theta_o}{g}$ i v`kU e`z DÇqb Kvj ubt`R Kti |

th`nZz $\frac{2}{g}$ a`eK, m`zivs $T \propto v_o \sin \theta_o$ A_` DÇqb Kvj e`z ubt`cb tetMi Dj `Dcvs`ki mgv`v`ZK |

Ab`y`gK পাল্লা

c`h` mgZtj ubt`cb l cZb ve`y ga`eZ`i-Z`K c`mi পাল্লা etj | পাল্লা`K R aiv nq| (3.21) mgxKi tY $y = 0$ emrtj, পাল্লা $x=R$ cvl qv hvte |

(3.21) mgxKi YvU n`Q $y = (\tan \theta_o)x - \frac{g}{2(v_o \cos \theta_o)^2} x^2$

$y = 0, x=R$ emtq,

$$0 = (\tan \theta_o) R - \frac{g}{2(v_o \cos \theta_o)^2} R^2$$

$$\therefore R = 0 \text{ A_ ev } R = \tan \theta_o \times \frac{2(v_o \cos \theta_o)^2}{g}$$

th`nZz $R = 0$ th `vb n`Z e` ubt`c Kiv nq tmB Ae`vb ubt`R Kti ZvB GuU M`b thvM` bq| AZGe,

$$\begin{aligned} R &= \tan \theta_o \frac{2(v_o \cos \theta_o)^2}{g} \\ &= \frac{\sin \theta_o}{\cos \theta_o} \cdot \frac{2v_o^2 \cos^2 \theta_o}{g} \\ &= \frac{2 \sin \theta_o \cos \theta_o}{g} \cdot v_o^2 \\ R &= \frac{v_o^2 \sin 2\theta_o}{g} \dots \dots \dots (3.26) \end{aligned}$$

মেলাক অব্যুগ পাল্লা

Dctii mgxkiY t_kK t`Lv hvq g a`e nI qvq Avw`teM v_o w`i _vKtj R Gi gvb wbt`qcy tKvY θ_o
Gi Dci wbf`Pkj | R মেলাক nte hLb sin 2θ_o মেলাক nte|

Avgi v Rwb, sin 2θ_o মেলাক +1 ntZ cwti; tm`q`T sin 2θ_o =1 ev, θ = 45°

A_`r wv`θ te`M wv`q`B GKw e`zমেলাক অব্যুগ `i-Z; AwZμg Ki`e hLb e`w অব্যুগ`Ki m`½
45° tKvY wv`q`B nte A_`r wbt`q`cb tKvY 45° ntj পাল্লা মেলাক nte|
মেলাক পাল্লার gvb

$$R_m = \frac{v_o^2 \sin 90^\circ}{g} = \frac{v_o^2}{g} \dots \dots \dots (3.27)$$

MwvZK mgm`vej x

D`niY 1

GKw cwtmi Avw` MwZteM 20ms⁻¹ Ges wbt`q`cb tKvY 30° cwtmUi (K) মেলাক D`PZv KZ nte? (L)
পাল্লা KZ? (M) wePiY Kvj KZ ?

mgvab t`q`v AvtQ v_o = 20 ms⁻¹; θ_o = 30°; g = 9.8 ms⁻¹

$$\begin{aligned} (K) \text{ মেলাক D`PZv } h_m &= \frac{(v_o \sin \theta_o)^2}{2g} \\ &= \frac{(20 \times \sin 30^\circ)^2}{2 \times 9.8} \\ &= \frac{(20 \times 0.5)^2}{2 \times 9.8} \\ &= 5.1 \text{ m} \end{aligned}$$

$$\begin{aligned} (L) \text{ অব্যুগ পাল্লা } R &= \frac{v^2 \sin 2\theta_o}{g} \\ &= \frac{(20\text{ms}^{-1})^2 \times (\sin 2 \times 30^\circ)}{9.8 \text{ ms}^{-2}} \\ &= \frac{20^2 \text{ m}^2 \text{ s}^{-2} \times 0.866}{9.8 \text{ ms}^{-2}} \\ &= 35.347 \text{ m} \end{aligned}$$

$$\begin{aligned}
 (M) \text{ nepib Kyj } T &= \frac{2v_o \sin \theta_o}{g} \\
 &= \frac{2 \times 20 \text{ ms}^{-1} \sin 30^\circ}{9.8 \text{ ms}^{-2}} \\
 &= \frac{2 \times 20 \text{ ms}^{-1} \times 0.5}{9.8 \text{ ms}^{-2}} \\
 &= 2.04 \text{ s}
 \end{aligned}$$

D`niY 2 t GKil c`tmi AvbyigK পাল্লা 48m Ges Am` teM 33 ms⁻¹ | `b`f`cY tKiv KZ?

mgvab t GLv`b t`qv AvtQ , AvbyigK পাল্লা R = 48m,

Am` teM v₀ = 33 ms⁻¹ , g = 9.8 ms⁻² `b`f`c tKiv θ₀ = ? ;

$$\text{Avgiv Rnb, } R = \frac{v_o^2 \sin 2\theta_o}{g}$$

$$\begin{aligned}
 \therefore \sin 2\theta_0 &= \frac{Rg}{v_o^2} \\
 &= \frac{48m \times 9.8ms^{-2}}{(33ms^{-1})^2} \\
 &= 0.43196
 \end{aligned}$$

$$\therefore 2\theta_0 = \sin^{-1}(0.43196) = 25.6^\circ$$

$$\therefore \theta_0 = \left(\frac{25.6}{2}\right)^\circ = 12.8^\circ$$

mvi mst`c

c`m t tKvb e`K AvbyigtKi mvt_ `zhR fite k`b` (evZv`m) `b`f`c Kiv ntj Zv`K c`m etj |

c`tmi Muz `ogv`K | Gi Muzc_ Aiae`vKvi | th tKvb `b`f`cb tetMi Rb` `b`f`cb tKiv 45⁰ ntj c`tmi AvbyigK পাল্লা me`ak nq | `b`f`cb tKiv 90° ntj c`mil উল্লস fite me`ak D`PZvq DVtZ cv`i |

$$\text{c`tmi Pj `i Lvi mgvKiY nj } y = x \tan \theta_o - \frac{g}{2v_o^2 \cos^2 \theta_o} x^2$$

cvtVÈi gj`vqb

mùVK DÈiùWi cvtk vJK vPy (v) w b|

1| cðtmi MùZ KZ gvñK?

(K) GKgvñK

(M) wñ gvñK

(L) wð gvñK

(N) gvñ vnxb

2| GKùJ cðtmi ZvrñWYK tetMi Awfgly tkvb w`tk?

(K) উল্লস w`tk

(M) wePiY c`_i j`^eivei

(L) AbyñgK w`tk

(N) wePiY c`_i `úkR eivei

3| GKùJ cðtmi Pj`tiLv`ùK ai`Yi?

(K) mij`tiLv`

(M) AweÈ

(L) eÈ

(N) DceÈ

4| cðtmi DÇqb Kvj` m`ùtk`Kvùù mùVK?

(K) Awñ tetMi উল্লস Dcistki mgvbzWZK|

(L) Awñ tetMi AbyñgK Dcistki mgvbzWZK|

(M) ZvrñWYK tetMi উল্লস Dcistki mgvbzWZK|

(N) ZvrñWYK tetMi AvbñgK Dcistki e`M` mgvbzWZK|

cW - 3

eĚxq MmZ

Dġġk

G cıřVi tkřl Avıcb-

- 1 eĚxq MmZi msÁv I D`vniY w`řZ cviřeb,
- 1 eĚxq MmZřZ `imLK I tKřmYK teřMi aviYv cıřeb Ges Gř`i gřa` mřúK`ıcb KiřZ cviřeb,
- 1 `imLK I tKřmYK teřMi exRMmYmZK Ges řř±i iřci mřúK`cKřk KiřZ cviřeb|

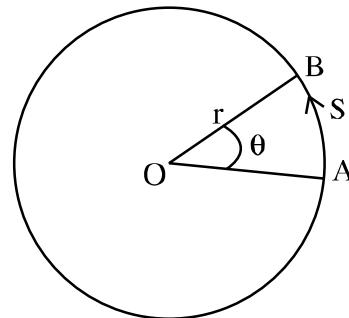
3.3.1 eĚxq MmZ

tKřb e`zev KYv tKřb mē`yev AřřřK tKř`aKři eĚvKři cř_ AvenZZ nřj Gi MmZřK eĚvKři MmZ ev eĚxq MmZ (Circular motion) eřj |

eĚxq MmZ GK aıřbi NYř MmZ | NYř hıř tKřb AřřřK tKř`aKři mřúvıř Z nq Zv nřj H AřřřK NYř Ařř (Axis of rotation) eřj | NYř hıř GKıU mē`řK tKř`aKři m`úvıř Z nq Zv nřj H mē`řK NYř tKř`a (Center of rotation) eřj | GKıU KYv eĚ cř_ NıřřZ `vKřj tKř`a I KYvi Ae`vb mřřhvMKřix mi j ři LvřK e`vmvřřř±i eřj |

aiv hvK, GKıU e`zeĚvKři cř_ NıřřZ NıřřZ tKřb GK mgq A Ae`řb t`řK B Ae`vb řcřQıj [ıPř 3.9 (K)] | e`řbi GB Ae`řbi cıřieZřřK Avgiv `yřře řveřřZ cıři |

1. e`zKYvıU eřřEi cıřııai Dci A t`řK B mē`řZ $AB = s$ `řZ; Aıřřřg KřiřQ | eĚ Pvc s %ııLK `řZ; hıř I GıU eř ti Lv | Gi cıřıgvc nře ıgıvı GKřK ev `řNř GKřK |



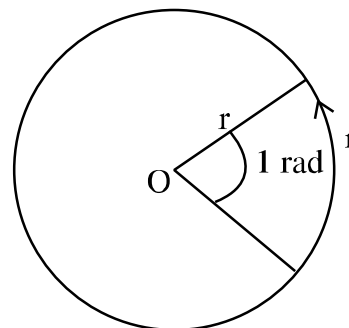
ıPř 3.9 (K)

2. e`ř eřřEi tKř`a th tKřv DrcbřKři Zvi mıřvřř` Avgiv e`řbi MmZ eYřv KiřřZ cıři | Gřřřřř tKř`a DrcbřřKřıřřK tKřmYK miY eřj | eĚxq MmZi řřřř tKřmYK miYřK θ řvıv cKřk Kiv hvq |

tKřmYK miY $\theta = \angle AOB$.

θ cıřıgřřci Rb` ti mVqvb GKK e`envı Kiv nq | mVııı e`envı Kiv thřřZ cıři | tKřb eřřEi e`vmvřřř mgvb eĚPvc tKř`a th tKřv DrcbřKři ZvřK GK ti mVqvb eřj | ıPř 3.9(L)

tKřb eřřEi cıřııı = $2\pi r$ A`ř cıřıııřřK Avgiv e`vmvřřř Gi mgvb `řNř 2π msLK eĚPřřc řıM KiřřZ cıři |



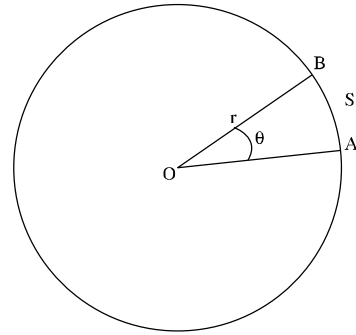
ıPř 3.9 (L)

GLb `řNř eĚPvc eřřEi tKř`a th tKřb DrcbřKři Zvi cıřıgvc 1 ti mVqvb

A_# ZvrqWYK tKšWYK teM

$$\omega = \lim_{\Delta t \rightarrow 0} \frac{\Delta \theta}{\Delta t} = \frac{d\theta}{dt} \quad (3.30)$$

ev, $\omega = \frac{d\theta}{dt} \dots \dots \dots (3.30)$



WpT 3.10

eÉvKvi c_uU m`úY©GKevi Ntj AvmtZ KYvUi th mgq jv#M Zv#K chqKvj etj | tKvb AveZ#kxj e`z chqKvj T ntj,

$$\omega = \frac{2\pi}{T} \dots \dots \dots (3.31)$$

c#Z tm#Kt#U e`z#Z_#jv cY#NY# m`úbaKti Zv#K K`úvK etj | GK chqKvj A_# T mgq m`úbaq 1u NY#

$$\therefore \text{GKK mgq m`úbaq } \frac{1}{T} \text{ msL`K NY#}$$

$$\therefore f = \frac{1}{T}$$

$$A_# \omega = 2\pi f \dots \dots \dots (3.32)$$

tKšWYK te#Mi gv#v: K`úvKtK 2π w`#j_#Y Ki#j tKšWYK teM cvl qv hvq | dtj tKšWYK te#M I K`úv#Ki gv#v GKB | GKvi#Y tKšWYK te#M#K tKšWYK K`úvKI ejv nq |

$$gv#v: tKšWYK te#Mi gv#v n#Q, \frac{tKvY}{gv#v} Gi gv#v |$$

$$tKšWYK teM = \frac{tKvY}{mgq} = \frac{Pvc}{e`vma^{\otimes} mgq} \quad [\because tKvY = \frac{Pvc}{e`vma^{\otimes}}]$$

$$\therefore [\omega] = \frac{L}{L \times T} = T^{-1}$$

$$\text{GKK : } tKšWYK te#Mi \text{ GKK} = \frac{tKvY}{mgq} \text{ Gi GKK} = \text{rad s}^{-1}$$

%dLK `vZ I tKšWYK `vZi m`úK©

aiv hvK r e`vmta# eÉvKvi c#_ GKvU e`z_ mg`vZtZ Nj#Q | mgM#eÉvKvi c_uU T tm#Kt#U e`z#Z GKevi Ntj Av#m |

Zv ntj e`z#Zi AvZμvš`%dLK `iZj = c#vwa = 2πr Ges tKšWYK `iZj = 2πr

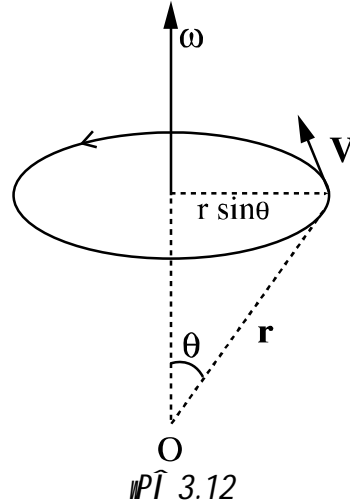
$$AZGe`i#LK `vZ = \frac{c`vwa}{ngq}$$

$$\text{ev, } v = \frac{2\pi r}{T} \dots \dots \dots (3.33)$$

^iMLK teM I tKŠvYK teM Mi m`úK©

aiv hvK GKwU e`zcn½ KvWtgv i z A†ŋi Dci AeW`Z O ve`šK tK`Kti XY mgZtj Nioi Kúvi
 mecixZ w`šK eÉvKvi ct_ NjtQ| th tKvb gytZ©Zvi ^iMLK teM v eÉvKvi ct_i th ve`šZ e`š A†Q
 tmB ve`šZ AwZ `úkR eivei |

Av†iv aiv hvK e`š i tKŠvYK teM ω| WbnwZ `E wbgg
 t_šK hvi w`K cvlqv hvq eÉvKvi ct_i Awfj x^Z_v z
 Aŋ eivei | cn½ KvWtgv i gj ve`ymvct†ŋ th tKvb
 gytZ©e`š i Ae`vb tf±i r (wPÍ 3.12) ntj eÉvKvi
 ct_i e`mva© r sinθ
 e`š i chŋKuj T ntj Zvi ^iMLK teM i gvb



$$v = \frac{2\pi r \sin\theta}{T} = \omega r \sin\theta \dots \dots \dots (3.36)$$

wKšz Ges r nt`Q `š tf±i Ges θ Z†`i Ašf,© tKvY |
 Kv†RB `š tf±i i vki tf±i , Yd†j i msÁv t_šK cvB,

$$\omega r \sin\theta = |\omega \times r|$$

$$ev, |v| = |\omega \times r|$$

Avei `š wU tf±i i vki tf±i , †Yi wbggvb††i ω×r Gi w`K Ges v Gi w`K GKB

$$\therefore v = \omega \times r \dots \dots \dots (3.37)$$

tKŠvYK ZjY

tKŠvYK teM i cwi eZ© ntj tKŠvYK ZjY nq| mg†qi m†_ Amg tKŠvYK teM i cwi eZ†bi nvi†K
 tKŠvYK ZjY e†j |

eÉvKvi ct_ Pj gvb e`KYvi tKŠvYK teM Δt mg†qi AeKv†k ω_i t_šK ω_f G cwi eWZŠ ntj Mo
 tKŠvYK ZjY,

$$\frac{\Delta\omega}{\Delta t} = \alpha$$

Ges Z†vŋwYK ZjY

$$\alpha = \lim_{\Delta t \rightarrow 0} \frac{\Delta\omega}{\Delta t} = \frac{d\omega}{dt} \dots \dots \dots (3.38)$$

$$tKŠvYK Zj†Yi g†v [\omega] = T^{-2}$$

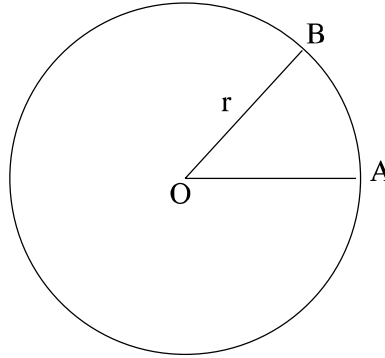
$$tKŠvYK Zj†Yi GKK ti wlvb/tm†KÚ^2 \text{ (rad s}^{-2}\text{)}$$

%iLK ZiY I tKŠVK ZiYi gta mpuK©

aiV hvK O me`jK tK`Kti GKwU e`z e`vmtaP eFvKvi ct_ Nj4Q| t_i mgtq e`#i Ae`vb A (iPÎ 3.13) me`jZ Ges Dnvi `iLK tetMi gvb v_i ,tKŠbK tetMi gvb ω_i

∴ v_i = ω_i r

aiV hvK t_f mgtq e`# B Ae`vb GtmtQ| GB Ae`vb `iLK I tKŠVK telM h_vμtg v_f Ges ω_f



iPÎ 3.13

∴ v_f = ω_f r

GLb tetMi cwieZ#bi Rb` `iLK ZiY a ntj

$$a = \frac{v_f - v_i}{t_f - t_i} = \frac{\omega_f r - \omega_i r}{t_f - t_i} = \frac{(\omega_f - \omega_i)r}{t_f - t_i} = \frac{\Delta\omega}{\Delta t} r = \alpha r$$

∴ a = αr (3.39)

mvi mst¶c

eFqx MvZ t tKvb e`zev KYv tKvb me`yev A¶iK tK`Kti eFct_ AveWZ ntj Gi MvZtK eFqx MvZ ev eFvKvi MvZ etj |

tKŠVK telM t eFqx MvZ m#ubctKvb e`z tKŠVK miYi nvi tK tKŠVK telM etj

$$\omega = \frac{d\theta}{dt}$$

tKŠVK ZiY t mgtqi m#_ Amg tKŠVK tetMi cwieZ#bi nvi tK tKŠVK ZiY etj |

$$\alpha = \frac{d\omega}{dt}$$

`iLK telM = tKŠVK telM × e`vma¶f±i

eV, v = ω × r

MwVZK mgm`ej x

D`niY 1t GKU t`qv Nnoi ngubtUi KvUvi `N^o18cm ntj Gi tKŠiYK teM Ges Gi cŃŠt`i mLK teM ubYq Ki`b|

mgvab t`l`qv AvtQ, chŃKij T = 1hr = 3600 s

$$KvUvi \text{ `N}^o_r = 18 \text{ cm} = 0.18 \text{ m}$$

$$tKŠiYK \text{ teM } \omega = ?$$

$$\%i\text{mLK teM } v = ?$$

$$\begin{aligned} \text{Avgiv Rmb, } \omega &= \frac{2\pi}{T} \\ &= \frac{2 \times 3.14 \text{ rad}}{3600 \text{ s}} \end{aligned}$$

$$= 1.74 \times 10^{-3} \text{ rad s}^{-1}$$

$$\text{Avevi } v = \omega r$$

$$= 1.74 \times 10^{-3} \text{ rad s}^{-1} \times 0.18 \text{ m}$$

$$= 3.13 \times 10^{-4} \text{ ms}^{-1}$$

D`niY 2 t eFivKvi ct_ 72 kmh⁻¹ mg `wZtZ Pj gvb tKvb Mvoxi tK>`gYx ZjiY 1 ms⁻² ntj eFivKvi ct_i e`imvaqKZ?

mgvab t`l`qv AvtQ,

$$\text{`wZ } v = 72 \text{ kmh}^{-1}$$

$$= 72 \times 10^3 \text{ m} \times (3600 \text{ S})^{-1}$$

$$= 20 \text{ ms}^{-1}$$

$$tK>`gYx \text{ ZjiY } a = 1 \text{ ms}^{-2}$$

$$e`imvaq = ?$$

$$\text{Avgiv Rmb, } a = \frac{v^2}{r}$$

$$\therefore r = \frac{v^2}{a} = \frac{(20 \text{ ms}^{-1})^2}{1 \text{ ms}^{-2}} = 400 \text{ m}$$

D`niY 3 t GKU e`wZK cvLvi mBP ŌAbŌ Kitj 10 evi cYNYŃbi ci cvLmUi tKŠiYK teM 20 rads⁻¹ nq tKŠiYK ZjiY KZ? [aŃi ubb th 10 evi cYNYŃbi cvLmU mg tKŠiYK teM cŃB nq]

mgvab t`l`qv AvtQ 10 evi cYNYŃbi tKŠiYK miY $\theta = 10 \times 2\pi \text{ rad} = 20\pi \text{ rad}$, tkl tKŠiYK teM

$$\omega_f = 20 \text{ rad s}^{-1}; \text{ cŃ} \text{ ugK tKŠiYK teM } \omega_i = 0 \text{ rad s}^{-1}, \text{ tKŠiYK ZjiY } \alpha = ?$$

$$\text{Avgiv Rmb, } \omega_f^2 = \omega_i^2 + 2\alpha\theta$$

$$2\alpha\theta = \omega_f^2 - \omega_i^2$$

$$\therefore \alpha = \frac{\omega_f^2 - \omega_i^2}{2\theta} = \frac{(20 \text{ rad s}^{-1})^2 - 0}{2 \times 20\pi \text{ rad}} = 3.183 \text{ rad s}^{-2}$$

cvtVĒi gj`vqb

mWK DĒġi i cġk WK Pý (√) w b|

1/ tKšwYK teġMi gvġv tKvbuU ?

- (K) LT^{-1} (L) LT^{-2}
- (M) T^{-1} (N) L^{-1}

2/ tKvb m`úK@U mWK bq?

- (K) $\omega = 2\pi n$ (L) $\omega = \frac{2\pi}{T}$
- (M) $v = \omega r$ (N) $v^2 = \omega r$

3/ eĒvKvi cġ_ Njġj tKšwYK teġMi w`K tKvbuU WK?

- (K) tKvb w`K bvB
- (L) eĒ mgZġj tK`^eivei AvbyngK
- (M) eġĒi tK`^Mrgx Ges NY@ Zġj i Dci j`^eivei
- (N) WbrwZ`Ē NY@bi w`K|

4/ GKwU KYv eĒvKvi cġ_ NjġZ_vKġj tK`^I KYvi Ae`vb msthwMKvix mij ġi LvġK WK eġj ?

- (K) NY@ Aġ (L) e`vma^o
- (M) e`vma^otf±i (N) tf±i Aġ

5/ o tK`^Ges r e`vma^oewkó eġĒi cwiwai Dci w`ġq MwZkxj e`KYv Δt mgq e`eavtb A t_ġK B Ae`vġb Gj e`KYvi`i wLK miYKZ?

- (K) AB PġC (L) ∠AOB
- (M) $\frac{\Delta\theta}{\Delta t}$ (N) $\omega = \frac{\angle AOB}{\Delta t}$

cW - 4

eĒxq Muzi mgxKiY I tK`gix ZjiY

Df`k`

G cv`Vi tk`I Av`cb

- 1/ eĒxq Muzi `ivLK I tKŠWK teM ci_Ŕ`/Zj`bv KitZ cv`teb,
- 1/ eĒxq Muzi mgxKiY`uj cŰZcv`b I eYŦv KitZ cv`teb,
- 1/ eĒxq Muzi tK`gix ZjiY e`vL`v I cwi gvc KitZ cv`teb|

3.4.1 eĒxq Muzi `ivLK I tKŠWK teM Zj`bv

G BD1bŦUi ce@ZPAbŦQ`_uj i Av`jvPbrq Avgiv tR`b1Q eĒxq Muzi`K `ivLK I tKŠWK Dfq f`teB cKvk Kiv hvq| c_w ex cŦŦi Dci w`tq A_ev mgŦ`mgZtj i Dci w`tq GKw Rvnr ceŦ`tK cwŦtq Pj`Z Pj`Z Av`Mi RvqMvq w`dŦi Gtj Zvi Muzi`K Avgiv `ivLK f`teB cKvk Kwi | wKŠzcKZ.cŦv`te Rvnr`Ri Muz eĒxq Muz, dtj GtK tKŠWK Muzi ivki gva`tgI cKvk KitZ cwi | tKŠWK I `ivLK teM Zj`bv KitZ tM`j Avgiv Gi m`k` Ges cv_Ŕ`_tjv Df`k` Kie|

(K) m`k`

- 1/ DfqB tF±i ivk
- 2/ AveZŦi Z KYvi `wZ evotj Df`qiB gv b ew`x cvq

(L) cv_Ŕ`

`ivLK teM	tKŠWK teM
1/ `ivLK miŦYi nvi`K `ivLK teM etj	1/ tKŠWK miŦYi nvi`K tKŠWK teM etj
2/ `ivLK teM gvŦv LT ⁻¹	2/ tKŠWK teM gvŦv T ⁻¹
3/ `ivLK teM GKK ms ⁻¹	3/ tKŠWK teM GKK rad s ⁻¹
4/ mgZjxq GKgvŦK I eĒxq Muz Dfq tŦj`ŦB cŦhvR`	4/ tKej gvŦ eĒxq Muzi tŦj`Ŧ cŦhvR`
5/ mg tKŠWK teM NYŦiZ `p e`z wewfbŦ KYvi `ivLK teM wewfbŦ	5/ mg tKŠWK teM NYŦiZ `p e`z cŦZ`K KYvi tKŠWK teM mgvb

3.4.2 t eĒxq Muzi mgxKiY

Avgiv wŦZxq Aa`v`q mij Ŧi Lvq MuzKxj e`z Muzi mgxKi Ymgr cŰZcv`b KŦi wQ| mgxKiY`uj nj

- i) $s = vt$
- ii) $v = u + at$
- iii) $s = ut + \frac{1}{2} at^2$
- iv) $v^2 = u^2 + 2as$

GKB Dcirtq Avgiv e f c t_ Muzkxj e - z t 7 t l Abijc mgxkiY c 0 Zc r ` b KitZ cvie | Avmly mgxkiY , yj c 0 Zc r ` b Kiv hvK |

(i) $\theta = \omega t$

ms Avbyvnti t mgtq tKvb e f xq c t_ Muzkxj e - z t K S W Y K mi Y θ ntj , Mo t K S W Y K teM $\omega = \frac{\theta}{t}$
 eV, $\theta = \omega t$ (3.40)

(ii) $\omega_f = \omega_i + \alpha t$

aiv hvK e f xq c t_ Muzkxj e - K Y vi t K S W Y K teM t mgq AeKv k ω_i t_ t K te to ω_f nj | Zvntj
 ms Avbyvnti , Mo t K S W Y K Zi Y $\alpha = \frac{\omega_f - \omega_i}{t}$
 eV, $\alpha t = \omega_f - \omega_i$
 eV, $\omega_f = \omega_i + \alpha t$ (3.41)

(iii) $\theta = \omega_i t + \frac{1}{2} \alpha t^2$

gtb Kw e f xq c t_ Muzkxj tKvb e - K Y vi c 0 u g K teM ω_i , t mgq e eavtb teM ω_f , t K S W Y K mi Y θ ,
 Mo t K S W Y K teM ω Ges mgZji Y α
 mgxkiY (3.40) t_ t K $\theta = \omega t$

eV, $\theta = \frac{\omega_i + \omega_f}{2} \times t$
 eV, $\theta = \frac{\omega_i + \omega_i + \alpha t}{2} \times t$
 eV, $\theta = \omega_i t + \frac{1}{2} \alpha t^2$ (3.42)

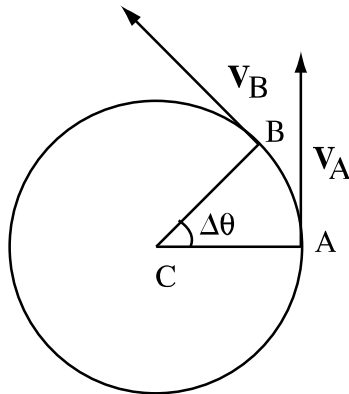
(iv) $\omega_f^2 = \omega_i^2 + 2\alpha\theta$

(3.41) mgxki t Yi Dfq c 7 t K eM K ti civB,

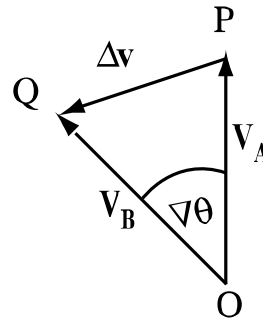
$\omega_f^2 = \omega_i^2 + 2\omega_i \alpha t + \alpha^2 t^2$
 eV, $\omega_f^2 = \omega_i^2 + 2\alpha (\omega_i t + \frac{1}{2} \alpha t^2)$
 eV, $\omega_f^2 = \omega_i^2 + 2\alpha\theta$ [3.41 ntZ $\omega_f = \omega_i + \alpha t$] (3.43)

3.4.3 mlyg eĚxq MvZ I tK`ġlyx ZiY

tKvb e`zKYv hLb mg`wZtZ tKvb eĚvKvi ct_ Njtz vtK ZLb Zvi MvZ tetMi gvb AcwiewZĚ vKtj I tetMi Awfgly cġZwbqZ e`tj hvq| MvZtem GKwU tfti i mK, Gi gvb I w`K AvtQ| gvb a`e vKtj i ayw`K cwiwZĚ ntj I tetMi cwiwZĚ mPZ nq| mZivs eSv hv`Q th, eĚvKvi ct_ mg`wZtZ avg`gvb KYvi GKwU ZiY AvtQ| Avgiv GLb GB ZiYi gvb I w`K wYġ Kie|



¶PĪ 3.14 (K)



¶PĪ 3.14 (L)

¶PĪ : 3.14 (K) G mlyg eĚvKvi MvZtZ MvZkxj GKwU e`zt`Lvb ntqtQ| aiv hvK t mg`q e`KvYwU eĚĒi cwiwai Dci A w`v`jz Ae`vb Kti | G mg`q Gi telM v_A eĚwU H w`v`jz AswKZ `úkR eivei w`v`qvkxj | Δt mg`qi e`eavtb e`w` B w`v`jz Gj | GB mg`q Gi telM v_B eĚĒi B w`v`jz AswKZ `úkR eivei w`v`qvkxj | aiv hvK A t`tK B w`v`jz thtZ tKSwYK miY Δθ LgB ¶ĪZ` e`zKYwU eĚxq ct_ mgvb`wZtZ Pj tQ|

AZGe v_A Ges v_B Gi gvb mgvb| w`KšGt`i Awfgly Avj v`v|

¶PĪ 3.14(L) tZ tKvb w`v`yo t`tK v_A Ges v_B tfti w`v`Rk tiLv h_v`m`g OP Ges OQ tUtB ΔOPQ m`v`ú`Kti tfti w`v`fB mĪ t`tK tetMi cwiwZĚ Δv w`v`Yġ Kiv ntqtQ

$v_B - v_A = \Delta v$ e`KvYvi `wZ mgvb etj , P I Q Lg KvQvKwQ ntj tj Lv hvq,
 $OP = OQ = v$

thtnZzΔθ tKvYwU LgB tQvU KvRb Δv Gi Awfgly v_A Ges v_B Dftqi m`v`B cġj p` A_¶ A w`v`jz AC eivei Z_v eĚĒi tK`C eivei e`w`i tetMi cwiwZĚ ev ZiY nq| GB ZiYtK tK`ġlyx ZiY etj |

%w`LK MvZ v_A Ges v_B Gi gvb mgvb A_¶ Gt`i gvtbi tKvb cwiwZĚ nt`Q bv| AZGe Gt`¶Ī A w`v`jz AC eivei ZiY, tetMi w`v`Ki cwiwZĚ NUvq| tK`ġlyx ej θviv m` GB ZiY e`K eĚct_ NYġgvb ti tL`Q| GB ZiY bv`v`Ktj e`z`úkR eivei mij tiLvq mg`tetM Pj tZ`v`KZ|

¶PĪ 3.14L tZ Δθ tKvYwU LgB ¶ĪZ` ZiY $|PQ| = |\Delta v| = v \sin \Delta \theta = v \Delta \theta$ [w`Kv -1 `be`]

GLv`b v nt`Q v_A Ges v_B Gi gvb, Av`MB D`v`v` Kiv ntqtQ e`w` mg`wZtZ Nj`Q etj Df`q gvbB mgvb|

GLb tK`ġlyx ZiY a_r ntj

$$a_r = \lim_{\Delta t \rightarrow 0} \frac{|\Delta v|}{\Delta t}$$

$$\begin{aligned}
 &= \lim_{\Delta t \rightarrow 0} \frac{v(\Delta\theta)}{\Delta t} \\
 &= v \lim_{\Delta t \rightarrow 0} \frac{\Delta\theta}{\Delta t} \\
 &= v \frac{d\theta}{dt} \\
 &= v\omega \dots \dots \dots (3.44)
 \end{aligned}$$

$\vec{v} = r\omega \vec{e}_\theta$, $\omega = \frac{v}{r}$
 $\therefore \vec{a}_r = -\omega^2 r \vec{e}_r = -\frac{v^2}{r} \vec{e}_r \dots \dots \dots (3.45)$

Ukvi 1 t pT 3.15 j q' Ki'b CA Ges CB eEi `m e'vma

$\angle AOB = \theta$ / aiv hvK, θ Auz q'z' / $BO \perp CA$

ti mqvB GKtK $\theta = \frac{PC \cdot AB}{e'vma(r)}$

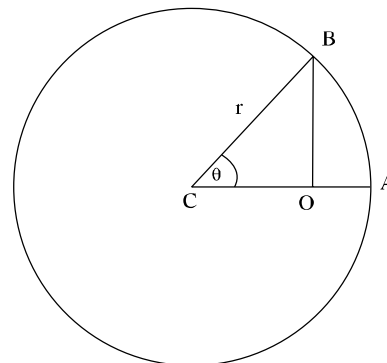
Avevi $\sin \theta = \frac{BO}{BC}$

θ Auz q'z' ZvB $BO \approx AB$ aiv hvq/

$\therefore \sin \theta = \frac{PC \cdot AB}{e'vma(r)}$

$\therefore \theta = \sin \theta$, hLb θ LvB q'z'

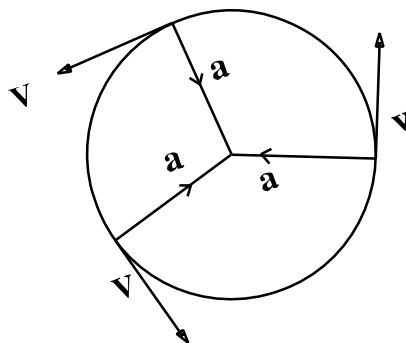
Avevi $\cos \theta = \frac{OC}{BC} \cong \frac{C}{BC} = \frac{r}{r} = 1$



pT 3.15

tK' g'lx ZjtYi D'niY

GKw mzi GK cš-GKw wj teta Aci cš-nvZ ti tL wj wtk e'vKvi ct_ Njyb hvq/ Gt q' t' nV cšqvRbq ej cšqvM Kti | GB etj i Rb' tK' g'lx ZjtY mjo nq/ e'lxq ct_ NYqgvb e'z' i mK tetMi gvb a'e _vKtj I KYw Dci G ZjtY wqv Kti |



pT 3.16

KYw hLb NjtZ _vtK ZLb Gi i mK tetMi w'K mgvMZ cwieZ' nq/ e'vKvi ct_i tKvb we'z' i mK tetMi w'K H we'z' AswKZ 'ukR eivei | teM tfzi i mK ZvB gvb a'e _vKv mEj i w'K cwieZ'bi Rb' tetMi cwieZ' nq/ tetMi GB cwieZ'bi Rb' ZjtY mjo nq/ e'vKvi ct_ KYvi th tKvb Ae'v' G ZjtY tK' g'lx | [pT 3.16]

mvivsk

tK`głx ZjYt eĖxq MuztZ MuzKxj cŃZ`KwU e`z`imLK`nZ a`e`vKtjI Gi tK`głx ZjYt e`gvb/GB ZjtYi Dm tK`głx ej hv e`z`muzi w`tki cwieZŃ NUvq/ dtj eĖxq MuztZ`imLK teM cŃZ gytZ`w`K cwieZŃ Kti A_Ń Muzi gvb a`e`vKtjI tK`głx ZjtYi dtj Muzi w`K cwieZŃ nq/ eĖxq Muzi tŃtŃ Muzi mgxKiY_sj nj :

- (i) $\theta = \omega t$
- (ii) $\omega_f = \omega_i + \alpha t$
- (iii) $\theta = \omega_i t + \frac{1}{2} \alpha t^2$
- (iv) $\omega_f^2 = \omega_i^2 + 2\alpha\theta$

Povš-gj`vqb cłkvj v

K. `beŃK cłot

mŃK DĖti i cłk ŃK Ńy Ńy (Ń) Ń b

1/ ZjY m`útkŃKŃKŃwU mŃK?

- (K) $a = \frac{dr}{dt}$
- (L) $a = \frac{ds}{dt}$
- (M) $a = \frac{dv}{dt}$
- (N) $a = \frac{d\omega}{dt}$

2/ cłmi teŃMi AbyŃgK Dcvtki Rb` tKŃwU mŃK

- (K) GKŃwU Ńw`Ń cłmi Rb` gvb a`eK
- (L) mKj cłmi Rb` gvb a`eK
- (M) gvb me`v cwieZŃKxj
- (N) gvb g Gi Dci ŃbŃŃKxj

3/ tKŃwYK ZjtYi gvTŃ tKŃwU ?

- (K) T^{-1}
- (L) T^{-2}
- (M) LT^{-2}
- (N) LT^{-1}

4/ `imLK teMtk eŃĖi e`vma`Ńv vŃM Kij ŃK cvl qv hvq?

- (K) tKŃwYK teM
- (L) tKŃwYK`nZ
- (M) tKŃwYK ZjY
- (N) tKŃwYK fi teM

L. mŃŃB-DĖi cłce

- 1/ mŃÁv Ńj Lj t cłm, cłmi পাল্লা, e`vma`Ńf±i, tKŃwYK miY, tKŃwYK teM, chŃKvj, tKŃwYK ZjY, tK`głx ZjY|
- 2/ Mo teM I ZvŃŃwYK teŃMi tŃ±i ifc DŃŃŃ Ki`b|
- 3/ ZjtYi DcvtK_sj t_ŃK ZjtYi gvb I Ń K ŃKfiŃe RŃv hvq ?
- 4/ ZvŃŃwYK ZjtYi Ń K tKŃw Ń K ?
- 5/ cłmi Pj ti Lv ŃKifc?

- 6/ GKU ctm meK D"PZvq DVtZ KZ mgq j vM?
- 7/ ctm meK D"PZvi mgxKiYU uK?
- 8/ ctm DÇqb Kvtj i mgxKiY tKvU ?
- 9/ KZ tKvY tKvb e⁻zbtqC Kij AvbyugK পাল্লা meK nq?
- 10/ tKSYK teMi GKK I gvIv mgxKiY ij Lb|
- 11/ tK>`gla ZjYi gvb tKvb tKvb ivki Dci ubfP Kti?
- 12/ `iLK ZjY I tKSYK ZjYi gta`mv`k` I m`uK`K uK?
- 13/ `iLK teM I tKSYK teMi Zjbr Ki`b|
- 14/ meK AvbyugK পাল্লার gvb KZ?

M. vek`-DEi ckt

- 1/ Muzi ubtge³ mgxKiY_{vj} cZcv`b Ki`b|
 (K) $v = v_0 + at$ (L) $r = r_0 + \frac{1}{2}(v_0 + v)t$ (M) $r = r_0 + v_0 t + \frac{1}{2} at^2$
- 2/ GKgnlK Muzi mgxKiY_{tjv} e`envi Kti Muzi mgxKiY_{tjvi} tf±i ifc cZcv`b Ki`b|
- 3/ GKU ctm Muzc+_i mgxKiY cZcv`b Ki`b|
- 4/ t`Lvb th GKU ctm Pj tiLv n`Q AwaeE|
- 5/ GKU ctm meK D"PZvq Ivi mgq, meK D"PZv I DÇqb Kvtj i Rb` ivkgyjv cZcv`b Ki`b|
- 6/ $v = \omega \times r$ m`uK`U cZcv`b Ki`b|
- 7/ tK>`gla ZjYi gvb I w`tki Rb` ivkgyjv ubYq Ki`b|
- 8/ mg tKSYK ZjY Muzkxj e⁻z tqtI cgvb Ki`b th,
 (i) $\omega_f = \omega_i + \alpha t$ (ii) $\theta = \omega_i t + \frac{1}{2} \alpha t^2$ (iii) $\omega_f^2 = \omega_i^2 + 2\alpha\theta$

N. MuvvZK mgn`v

- 1/ GKU ctm AvbyugK পাল্লা 79.53 m Ges uePiYKij 5.35 tm. ubtqcb teM I ubtqcb tKvY ubYq Ki`b|
- 2/ GKU e`K 4ms⁻¹ teM Ges 35⁰ ubtqcb tKvY ktb` ubtqC Kiv ntjv | Klb e`bi teMi Awfgy AvbyugK nte?
- 3/ GKU KYv 1.5 m e`vmtaP GKU eFvki c+_ cZ ugubtU 120 evi AveZ Kti | KYvUj (K) chqKij KZ? (L) tKSYK teM KZ? (M) ti`iLK teM KZ?
- 4/ nvZ Nvui tmtKtUi KvUvi `N`9.7 cm ntj Gi cts+ `iLK teM ubYq Ki`b|
- 5/ 0.05 Kg fti GKU e`K 0.3 m `xN`mzvi GK cts-teta eFvki c+_ cZ tmtKtU 3 evi Njvtr n`Q| Gi tK>`gla ZjY KZ?